

# Fixed Point Theorem of Gregus Type in $d$ -Metric Space

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**Abstract:** In this article, a common fixed point theorem for a pair of self-mapping is establish in  $d$ -metric space using (CLR) property. Our establish theorem extend, generalize and improve similar type of results of the literature in the setting of  $d$ -metric space.

**Keywords:**  $d$ -metric space, (CLR) property, weakly compatible mappings, property (E.A).

## 1 Introduction

In 1922, Banach established a fixed point result in complete metric space for a contraction mapping, which is one of the most important result of functional analysis. As a part of study of denotational semitics and data flow network Mathews [1] generalized Banach contraction principle in partial metric space (pms).

Hitzler [2], initiated the idea of dislocated metric ( $d$ -metric) space and established fixed point theorem of Banach type in such a space. Results on fixed point for compatible and weakly compatible mappings introduced by Jungck in [3,4] are established in [5,6]. In [7], Aamri and EI-Moutawakil initiated the idea of property (E.A), while Sintunavarat and Kuman in [8] introduced the concept of (CLR) property. In the above mentioned concepts the later one is superior then the previous one.

Gregus [9] established a result on fixed point in Banach space. Several authors generalized such a theorem in different spaces (see [10,11,12]). Using the idea of weakly compatible, (CLR) property and property (E.A) there we have proved fixed point theorem of Gregous type in  $d$ -metric space. For the support of our constructed results an example is provided.

## 2 Preliminaries

**Definition.** [2]. Consider  $d_1 : X_0 \times X_0 \rightarrow \mathbb{R}^+ \cup \{0\}$  be a function on a non-empty set  $X_0$  satisfying

$$1) d_1(x_1, y_1) = d_1(y_1, x_1) = 0 \text{ implies } x_1 = y_1;$$

$$2) d_1(x_1, y_1) = d_1(y_1, x_1);$$

$$3) d_1(x_1, y_1) \leq d_1(x_1, z_1) + d_1(z_1, y_1) \text{ for all } x_1, y_1, z_1 \in X_0.$$

Then  $d_1$  is a  $d$ -metric on  $X_0$  and  $(X_0, d_1)$  is a  $d$ -metric space.

**Example.** Suppose  $X_0 = \mathbb{R}^+$ . A function  $d_1 : X_0 \times X_0 \rightarrow \mathbb{R}^+ \cup \{0\}$  defined by

$$d_1(x_0, y_0) = x_0 + y_0 \text{ for all } x_0, y_0 \in X_0.$$

**Definition.** Suppose  $S_0$  and  $T_0$  be self-mappings on  $X_0$  which is non-empty then

1. A point  $x_0 \in X_0$  is called fixed point of  $T_0$  if  $T_0x_0 = x_0$ .

2. A point  $x_0 \in X_0$  is known as coincidence point of  $S_0$  and  $T_0$  if  $S_0x_0 = T_0x_0$  and we said  $u_0 = S_0x_0 = T_0x_0$  is a point of coincidence.

3. A point  $x_0 \in X_0$  is known as fixed point of both  $S_0$  and  $T_0$  if  $S_0x_0 = T_0x_0 = x_0$ .

**Definition.** Mappings  $S_0$  and  $T_0$  of a  $d$ -metric space  $(X_0, d_0)$  are known to be compatible if

$$\lim_{n \rightarrow \infty} d_0(S_0T_0x_n, T_0S_0x_n) = 0$$

when there exists a sequence  $\{x_n\}$  in  $X_0$  such that

$$\lim_{n \rightarrow \infty} S_0x_n = \lim_{n \rightarrow \infty} T_0x_n = t_0$$

for some  $t_0$  in  $X_0$ .

**Definition.** Mappings  $S_0$  and  $T_0$  on a  $d$ -metric space  $(X_0, d_0)$  are said to be weakly compatible if they commute at all of their coincidence points i.e if  $S_0u_0 = T_0u_0$  for some  $u_0 \in X_0$  then  $S_0T_0u_0 = T_0S_0u_0$ .

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**Definition.** [7]. Mappings  $S_0$  and  $T_0$  on a  $d$ -metric space  $(X_0, d_0)$  are said to satisfy property (E.A) if there exists a sequence  $\{t_n\}$  in  $X_0$  such that

$$\lim_{n \rightarrow \infty} S_0 t_n = \lim_{n \rightarrow \infty} T_0 t_n = t_0$$

for some  $t_0$  in  $X_0$ .

**Example.** Consider  $X_0 = [0, 1]$  with  $d$ -metric given by

$$d_0(x_0, y_0) = x_0 + y_0 \quad \text{for all } x_0, y_0 \in X_0.$$

The self-mappings  $S_0$  and  $T_0$  on  $X_0$  are defined by

$$S_0 x_0 = \begin{cases} 1 - x_0 & \text{if } x_0 \in [0, \frac{1}{2}] \\ 0 & \text{if } x_0 \in (\frac{1}{2}, 1] \end{cases}$$

and

$$T_0 x_0 = \begin{cases} \frac{1}{2} & \text{if } x_0 \in [0, \frac{1}{2}] \\ \frac{3}{4} & \text{if } x_0 \in (\frac{1}{2}, 1] \end{cases}$$

for a sequence  $t_n = \frac{1}{2} - \frac{1}{n}$  in  $X_0$  with  $n \geq 2$  hold property (E.A) as

$$\lim_{n \rightarrow \infty} S_0 t_n = \lim_{n \rightarrow \infty} T_0 t_n = \frac{1}{2} \in X_0.$$

Also  $S_0$  and  $T_0$  are weakly compatible as they commute at  $\frac{1}{2}$  which is the only coincidence point of  $S_0$  and  $T_0$  but not compatible because

$$\lim_{n \rightarrow \infty} d_0(S_0 T_0 t_n, T_0 S_0 t_n) \neq 0.$$

**Definition.** [8]. Mappings  $S_0$  and  $T_0$  on a  $d$ -metric space  $(X_0, d_0)$  are said to satisfy (CLR) property if there exists a sequence  $\{t_n\}$  in  $X_0$  such that

$$\lim_{n \rightarrow \infty} S_0 t_n = \lim_{n \rightarrow \infty} T_0 t_n = T_0 u_0$$

for some  $u_0$  in  $X_0$ .

**Example.** Suppose  $X_0 = \mathbb{R}^+ \cup 0$ , with  $d$ -metric space on  $X_0$  is given by

$$d_0(x_0, y_0) = x_0 + y_0 \quad \text{for all } x_0, y_0 \in X_0.$$

Mappings  $S_0$  and  $T_0$  are given by

$$S_0 x_0 = \frac{x_0}{2} \quad \text{and} \quad T_0 x_0 = 2x_0 \quad \forall x_0 \in X_0.$$

Suppose a sequence  $t_n = \frac{1}{n}$

$$\lim_{n \rightarrow \infty} S_0 t_n = \lim_{n \rightarrow \infty} T_0 t_n = t_0.$$

Thus  $S_0$  and  $T_0$  hold (CLR) property.

**Remark.** It is clear from Jungck [3] definition that two self-mappings are said to be non-compatible if there exist at least one sequence  $\{x_n\}$  in  $X$  such that

$$\lim_{n \rightarrow \infty} S_0 x_n = \lim_{n \rightarrow \infty} T_0 x_n = t \quad \text{for some } t \in X.$$

but  $\lim_{n \rightarrow \infty} d(ST_0 x_n, T_0 S_0 x_n)$  either not equal to zero or does not exist. Therefore, two non-compatible mappings satisfy property (E.A).

### 3 Main Results

**Theorem.** Suppose  $S_0$  and  $T_0$  be weakly compatible mappings on  $d$ -metric space  $(X_0, d_0)$  satisfying

1.  $S_0$  and  $T_0$  satisfy (CLR) property;
2.  $d_0^p(S_0 x_0, S_0 y_0) \leq \alpha d_0^p(T_0 x_0, T_0 y_0) + \beta \max \left\{ d_0^p(S_0 x_0, T_0 x_0), d_0^p(S_0 y_0, T_0 y_0) \right\} + \gamma \max \left\{ d_0^p(T_0 x_0, T_0 y_0), d_0^p(S_0 x_0, T_0 x_0), d_0^p(S_0 y_0, T_0 y_0) \right\}$ ;

for all  $x_0, y_0 \in X_0$ ,  $\alpha, \beta, \gamma \geq 0$  for  $2(\alpha + \beta + \gamma) < 1$  and  $p \geq 1$ . Then  $S_0$  and  $T_0$  have a fixed point which is unique and common to both of the mappings.

**Proof.** Since  $S_0$  and  $T_0$  hold (CLR) property therefore there exists a sequence  $\{l_n\}$  in  $X_0$  such that

$$\lim_{n \rightarrow \infty} S_0 l_n = \lim_{n \rightarrow \infty} T_0 l_n = T_0 u_0 \quad (1)$$

for any  $u_0$  in  $X_0$ .

To show that  $S_0 u_0 = T_0 u_0$  for this suppose

$$\begin{aligned} d_0^p(S_0 l_n, S_0 u_0) &\leq \alpha d_0^p(T_0 l_n, T_0 u_0) + \\ &\beta \max \left\{ d_0^p(S_0 l_n, l_n), d_0^p(S_0 u_0, T_0 u_0) \right\} + \\ &\gamma \max \left\{ d_0^p(T_0 l_n, T_0 u_0), d_0^p(S_0 l_n, T_0 l_n), d_0^p(S_0 u_0, T_0 u_0) \right\}. \end{aligned}$$

Taking limit  $n \rightarrow \infty$  and using (1) we have

$$\begin{aligned} d_0^p(T_0 u_0, S_0 u_0) &\leq \alpha d_0^p(T_0 u_0, T_0 u_0) + \\ &\beta \max \left\{ d_0^p(T_0 u_0, T_0 u_0), d_0^p(S_0 u_0, T_0 u_0) \right\} + \\ &\gamma \max \left\{ d_0^p(T_0 u_0, T_0 u_0), d_0^p(T_0 u_0, T_0 u_0), d_0^p(S_0 u_0, T_0 u_0) \right\}. \end{aligned} \quad (2)$$

$$d_0^p(T_0 u_0, T_0 u_0) \leq d_0^p(T_0 u_0, S_0 u_0) + d_0^p(S_0 u_0, T_0 u_0).$$

Using symmetric property we have

$$d_0^p(T_0 u_0, T_0 u_0) \leq 2d_0^p(T_0 u_0, S_0 u_0). \quad (3)$$

Using (3) in (2) we have

$$d_0^p(T_0 u_0, S_0 u_0) \leq 2(\alpha + \beta + \gamma) d_0^p(T_0 u_0, S_0 u_0)$$

which create a contradiction because  $2(\alpha + \beta + \gamma) < 1$ . Therefore, the above inequality is hold only if  $d_0^p(T_0 u_0, S_0 u_0) = 0$  using symmetric property  $d_0^p(S_0 u_0, T_0 u_0) = 0$  we get  $S_0 u_0 = T_0 u_0$ .

Because  $S_0$  and  $T_0$  are mappings which are weakly compatible thus

$$S_0 u_0 = T_0 u_0 \Rightarrow S_0 T_0 u_0 = T_0 S_0 u_0.$$

Therefore

$$S_0S_0u_0 = T_0S_0u_0 = S_0T_0u_0. \tag{4}$$

Now to prove that  $S_0u_0$  is the fixed point of  $S_0$  and  $T_0$  common to both of them. Assume

$$\begin{aligned} & d_0^p(S_0u_0, S_0S_0u_0) \leq \alpha d_0^p(T_0u_0, T_0S_0u_0) + \\ & \beta \max \left\{ d_0^p(S_0u_0, T_0u_0), d_0^p(S_0S_0u_0, T_0S_0u_0) \right\} + \\ & \gamma \max \left\{ d_0^p(T_0u_0, T_0S_0u_0), d_0^p(S_0u_0, T_0u_0), \right. \\ & \left. d_0^p(S_0S_0u_0, T_0S_0u_0) \right\}. \end{aligned}$$

Using (4) and the fact that  $S_0u_0 = T_0u_0$  we have

$$\begin{aligned} & d_0^p(S_0u_0, S_0S_0u_0) \leq \alpha d_0^p(S_0u_0, S_0S_0u_0) + \\ & \beta \max \left\{ d_0^p(S_0u_0, S_0u_0), d_0^p(S_0S_0u_0, S_0S_0u_0) \right\} + \\ & \gamma \max \left\{ d_0^p(S_0u_0, S_0S_0u_0), d_0^p(S_0u_0, S_0u_0), \right. \\ & \left. d_0^p(S_0S_0u_0, S_0S_0u_0) \right\}. \tag{5} \end{aligned}$$

Since

$$d_0^p(S_0u_0, S_0u_0) \leq d_0^p(S_0u_0, S_0S_0u_0) + d_0^p(S_0S_0u_0, S_0u_0).$$

By symmetric property we have

$$d_0^p(S_0u_0, S_0u_0) \leq 2d_0^p(S_0u_0, S_0S_0u_0). \tag{6}$$

Similarly we can show that

$$d_0^p(S_0S_0u_0, S_0S_0u_0) \leq 2d_0^p(S_0u_0, S_0S_0u_0). \tag{7}$$

Using (6) and (7) in (5) we have

$$d_0^p(S_0u_0, S_0S_0u_0) \leq (\alpha + 2(\beta + \gamma))d_0^p(S_0u_0, S_0S_0u_0)$$

which is a contradiction therefore  $d_0^p(S_0u_0, S_0S_0u_0) = 0$  also by symmetric property  $d_0^p(S_0S_0u_0, S_0u_0) = 0$  implies  $S_0S_0u_0 = S_0u_0$ . Also by (4)  $T_0S_0u_0 = S_0u_0$ . Thus  $S_0u_0$  is the fixed point of  $S_0$  and  $T_0$  which is common to both of them.

**Uniqueness.** Suppose  $u_0 \neq v_0$  be differen fixed points of  $S_0$  and  $T_0$  and common to both of theses mappings. Using (2) we get

$$\begin{aligned} & d_0^p(u_0, v_0) = d_0^p(S_0u_0, S_0v_0) \leq \alpha d_0^p(T_0u_0, T_0v_0) + \\ & \beta \max \left\{ d_0^p(S_0u_0, T_0u_0), d_0^p(S_0v_0, T_0v_0) \right\} + \\ & \gamma \max \left\{ d_0^p(T_0u_0, T_0v_0), d_0^p(S_0u_0, T_0u_0), d_0^p(S_0v_0, T_0v_0) \right\} \end{aligned}$$

$$\begin{aligned} & \leq \alpha d_0^p(u_0, v_0) + \beta \max \left\{ d_0^p(u_0, u_0), d_0^p(v_0, v_0) \right\} + \\ & \gamma \max \left\{ d_0^p(u_0, v_0), d_0^p(u_0, u_0), d_0^p(v_0, v_0) \right\}. \end{aligned}$$

Again since

$$d_0^p(u_0, u_0) \leq 2d_0^p(u_0, v_0) \text{ and } d_0^p(v_0, v_0) \leq 2d_0^p(u_0, v_0).$$

Hence the above inequality takes the form

$$d_0^p(u_0, v_0) \leq (\alpha + 2(\beta + \gamma))d_0^p(u_0, v_0)$$

which create again a contradiction which implies  $d_0^p(u_0, v_0) = 0$  and using symmetric property we get  $d_0^p(v_0, u_0) = 0$  implies  $u_0 = v_0$ . Thus fixed point of  $S_0$  and  $T_0$  is unique.

The following corollaries are deduced from the above theorem.

**Corollary.** Suppose  $S_0$  and  $T_0$  be mappings which are weakly compatible on  $d$ -metric space  $(X_0, d_0)$  satisfying

1.  $S_0$  and  $T_0$  hold (CLR) property;
2.  $d_0(S_0x_0, S_0y_0) \leq \alpha d_0(T_0x_0, T_0y_0) + \beta \max \left\{ d_0(S_0x_0, T_0x_0), d_0(S_0y_0, T_0y_0) \right\} + \gamma \max \left\{ d_0(T_0x_0, T_0y_0), d_0(S_0x_0, T_0x_0), d_0(S_0y_0, T_0y_0) \right\}$ ;

for all  $x_0, y_0 \in X_0$ ,  $\alpha, \beta, \gamma \geq 0$  for  $2(\alpha + \beta + \gamma) < 1$ . Then  $S_0$  and  $T_0$  have fixed point which is unique and common to both of the mappings.

**Corollary.** Consider  $S_0$  and  $T_0$  be mappings which are weakly compatible on  $d$ -metric space  $(X_0, d_0)$  satisfying

1.  $S_0$  and  $T_0$  hold (CLR) property;
2.  $d_0^p(S_0x_0, S_0y_0) \leq \alpha d_0^p(T_0x_0, T_0y_0) + \beta \max \left\{ d_0^p(S_0x_0, T_0x_0), d_0^p(S_0y_0, T_0y_0) \right\}$ ;

for all  $x_0, y_0 \in X_0$ ,  $\alpha, \beta \geq 0$  for  $2(\alpha + \beta) < 1$  and  $p \geq 1$ . Then  $S_0$  and  $T_0$  have fixed point which is unique and common to both of the mappings.

**Corollary.** Suppose  $S_0$  and  $T_0$  be mappings on  $d$ -metric space  $(X_0, d_0)$  which are weakly compatible satisfying

1.  $S_0$  and  $T_0$  hold (CLR) property;
2.  $d_0^p(S_0x_0, S_0y_0) \leq \alpha d_0^p(T_0x_0, T_0y_0)$ ;

for all  $x_0, y_0 \in X_0$ ,  $\alpha \geq 0$  for  $2\alpha < 1$  and  $p \geq 1$ . Then  $S_0$  and  $T_0$  have fixed point which is unique and common to both of the mappings.

**Example.** Consider  $X_0 = [0, 1]$  with  $d$ -metric on  $X_0$  is given by

$$d_0(x_0, y_0) = x_0 + y_0 \text{ for all } x_0, y_0 \in X_0.$$

The self-mappings  $S_0$  and  $T_0$  are defined by

$$S_0x_0 = \frac{x_0}{4} \text{ and } T_0x_0 = x_0 \text{ for all } x_0 \in X_0.$$

Clearly  $S_0$  and  $T_0$  satisfy (CLR) property by selecting  $\{l_n\} = \frac{1}{n}$ .

$$\lim_{n \rightarrow \infty} S_0 l_n = \lim_{n \rightarrow \infty} T_0 l_n = t_0.$$

Also  $S_0$  and  $T_0$  are weakly compatible because

$$S_0 0 = T_0 0 \Rightarrow S_0 T_0 0 = T_0 S_0 0.$$

$$d_0^p(S_0 x_0, S_0 y_0) = \frac{x_0}{4} + \frac{y_0}{4} \leq \frac{1}{6}(x_0 + y_0) = \alpha d_0^p(x_0, y_0).$$

Thus all the conditions of last corollary are satisfied for  $\frac{1}{6} \leq \alpha < 1$  having 0 is the fixed point of  $S_0$  and  $T_0$  which is unique and common to both the mappings.

Now we prove a common fixed point theorem for a pair of weakly compatible mappings using property (E.A) with additional condition of closeness of the subspace.

**Theorem.** Consider  $S_0$  and  $T_0$  be mappings on  $d$ -metric space  $(X_0, d_0)$  which are weakly compatible satisfying

$$\begin{aligned} & 1. S_0 \text{ and } T_0 \text{ hold property (E.A);} \\ & 2. d_0^p(S_0 x_0, S_0 y_0) \leq \alpha d_0^p(T_0 x_0, T_0 y_0) + \\ & \quad \beta \max \left\{ d_0^p(S_0 x_0, T_0 x_0), d_0^p(S_0 y_0, T_0 y_0) \right\} + \\ & \quad \gamma \max \left\{ d_0^p(T_0 x_0, T_0 y_0), d_0^p(S_0 x_0, T_0 x_0), d_0^p(S_0 y_0, T_0 y_0) \right\}; \end{aligned}$$

for all  $x_0, y_0 \in X_0$ ,  $\alpha, \beta, \gamma \geq 0$  for  $2(\alpha + \beta + \gamma) < 1$  and  $p \geq 1$ . If  $T_0(X_0)$  is a closed subspace of  $X_0$ . Then  $S_0$  and  $T_0$  have fixed point which is unique and common to both the mappings.

**Proof.** Because  $S_0$  and  $T_0$  hold property (E.A), so there must exists a sequence  $\{l_n\}$  in  $X_0$  such that

$$\lim_{n \rightarrow \infty} S_0 l_n = \lim_{n \rightarrow \infty} T_0 l_n = t_0 \text{ for some } t_0 \in X_0.$$

$T_0(X_0)$  is a closed subspace of  $X_0$ , thus there must exists  $u_0 \in X_0$  such that  $T_0 u_0 = t_0$ . Thus  $S_0$  and  $T_0$  hold (CLR) property and so by previous  $S_0$  and  $T_0$  have fixed point which is unique and common to both the mappings.

The following corollaries are deduced from the above theorem.

**Corollary.** Suppose  $S_0$  and  $T_0$  be mappings on  $d$ -metric space  $(X_0, d_0)$  which are weakly compatible satisfying

$$\begin{aligned} & 1. S_0 \text{ and } T_0 \text{ hold property (E.A);} \\ & 2. d_0(S_0 x_0, S_0 y) \leq \alpha d_0(T_0 x_0, T_0 y_0) + \\ & \quad \beta \max \left\{ d_0(S_0 x_0, T_0 x_0), d_0(S_0 y_0, T_0 y_0) \right\} + \\ & \quad \gamma \max \left\{ d_0(T_0 x_0, T_0 y_0), d_0(S_0 x_0, T_0 x_0), d_0(S_0 y_0, T_0 y_0) \right\}; \\ & 3. S_0(X_0) \subset T_0(X_0); \end{aligned}$$

for all  $x_0, y_0 \in X_0$ ,  $\alpha, \beta, \gamma \geq 0$  for  $2(\alpha + \beta + \gamma) < 1$ . If  $T_0(X_0)$  is a closed subspace of  $X_0$ . Then  $S_0$  and  $T_0$  have a fixed point which is common to both mappings and unique.

**Corollary.** Suppose  $S_0$  and  $T_0$  be mappings on  $d$ -metric space  $(X_0, d_0)$  which are weakly compatible satisfying

$$1. S_0 \text{ and } T_0 \text{ hold property (E.A);}$$

$$\begin{aligned} & 2. d_0(S_0 x_0, S_0 y_0) \leq \alpha d_0(T_0 x_0, T_0 y_0) + \\ & \quad \beta \max \left\{ d_0(S_0 x_0, T_0 x_0), d_0(S_0 y_0, T_0 y_0) \right\}; \\ & 3. S_0(X_0) \subset T_0(X_0); \end{aligned}$$

for all  $x_0, y_0 \in X_0$ ,  $\alpha, \beta \geq 0$  for  $2(\alpha + \beta) < 1$ . If  $T_0(X_0)$  is a closed subspace of  $X_0$ . Then  $S_0$  and  $T_0$  have fixed point which is unique and common to both the mappings.

**Corollary.** Consider  $S_0$  and  $T_0$  be mappings on  $d$ -metric space  $(X_0, d_0)$  which are weakly compatible satisfying

$$\begin{aligned} & 1. S_0 \text{ and } T_0 \text{ hold property (E.A);} \\ & 2. d_0(S_0 x_0, S_0 y_0) \leq \alpha d_0(T_0 x_0, T_0 y_0); \\ & 3. S_0(X_0) \subset T_0(X_0); \end{aligned}$$

for all  $x_0, y_0 \in X_0$ ,  $\alpha \geq 0$  for  $2\alpha < 1$ . If  $T_0(X_0)$  is a closed subspace of  $X_0$ . Then  $S_0$  and  $T_0$  have fixed point which is unique and common to both the mappings.

## 4 Conclusion

Our constructed theorems extend, generalize and improve the results established by Gregus [9], Fisher and Sessa [10], Jungck [11] and Diwan and Gupta [12] in the frame work of  $d$ -metric space. In case of (CLR) property completeness (closeness) of the space or subspace is not necessary. Moreover, in case of using (CLR) property containment of ranges of the involved mappings is not necessarily required.

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