

Coupled Coincidence Point Results on Partial Metric Spaces

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Abstract: In this paper, we consider a new class of pairs of generalized contractive type mappings defined in partial metric spaces. Some coincidence and common fixed point results for these mapping are presented.

Keywords: Partial metric space, coincidence point, coupled fixed point, common coupled fixed point, Generalized contraction principle.

1 Introduction and Preliminaries

In 1992, Matthews [16,17] introduced the notion of a partial metric space which is a generalized metric space in which each object does not necessarily have to have a zero distance from itself.

First, we start with some preliminaries definitions on the partial metric spaces [1,2,3,4,5,6,8,10,11,12,13,14,16,17,18,19,20,21,22,23,24,25,26,27,28,29,30,31,32].

Definition 1.[16, 17] A partial metric on a nonempty set X is a function $p : X \times X \rightarrow R^+$ such that for all $x, y, z \in X$:

$$(P_1) x = y \Leftrightarrow p(x, x) = p(x, y) = p(y, y),$$

$$(P_2) p(x, x) \leq p(x, y),$$

$$(P_3) p(x, y) = p(y, x),$$

$$(P_4) p(x, y) \leq p(x, z) + p(z, y) - p(z, z).$$

A partial metric space is a pair (X, p) such that X is a nonempty set and p is a partial metric on X .

Remark. It is clear that, if $p(x, y) = 0$, then from (P_1) and (P_2) $x = y$. But if $x = y$, $p(x, y)$ may not be 0.

Example 1. Let a function $p : R^+ \times R^+ \rightarrow R^+$ be defined by $p(x, y) = \max\{x, y\}$ for any $x, y \in R^+$. Then, (R^+, p) is a partial metric space.

Example 2. If $X = \{[a, b] : a, b \in R, a \leq b\}$, then $p : X \times X \rightarrow R^+$ defined by $p([a, b], [c, d]) = \max\{b, d\} - \min\{a, c\}$ defines a partial metric on X .

Each partial metric p on X generates a T_0 topology τ_p on X which has as a base the family open p -balls $\{B_p(x, \varepsilon) : x \in X, \varepsilon > 0\}$, where $B_p(x, \varepsilon) = \{y \in X : p(x, y) < p(x, x) + \varepsilon\}$ for all $x \in X$ and $\varepsilon > 0$.

If p is a partial metric on X , then the function $p^s : X \times X \rightarrow R^+$ given by

$$p^s(x, y) = 2p(x, y) - p(x, x) - p(y, y) \quad (1)$$

is a metric on X .

Definition 2.[16, 17]

(i) A sequence $\{x_n\}$ in a partial metric space (X, p) converges to a point $x \in X$ if

$$p(x, x) = \lim_{n \rightarrow \infty} p(x, x_n),$$

(ii) a sequence $\{x_n\}$ in a partial metric space (X, p) is called a Cauchy sequence if there exists (and is finite)

$$\lim_{n, m \rightarrow \infty} p(x_m, x_n),$$

(iii) a partial metric space (X, p) is said to be complete if every Cauchy sequence $\{x_n\}$ in X converges, with respect to τ_p , to a point $x \in X$ such that

$$p(x, x) = \lim_{n, m \rightarrow \infty} p(x_m, x_n).$$

Remark. It is easy to see that, every closed subset of a complete partial metric space is complete.

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Lemma 101[16, 17] Let (X, p) be a partial metric space. Then

- (a) $\{x_n\}$ is a Cauchy sequence in (X, p) if and only if it is a Cauchy sequence in the metric space (X, p^s) .
 (b) A partial metric space (X, p) is complete if and only if the metric space (X, p^s) is complete. Furthermore,

$$\lim_{n \rightarrow \infty} p^s(x_n, x) = 0$$

if and only if

$$p(x, x) = \lim_{n \rightarrow \infty} p(x, x_n) = \lim_{n, m \rightarrow \infty} p(x_m, x_n).$$

Lemma 102[4] A mapping $f : X \rightarrow X$ is said to be continuous at $a \in X$, if for every $\varepsilon > 0$, there exists $\delta > 0$ such that $f(B(a, \delta)) \subset B(f(a), \varepsilon)$.

The following result is easy to check.

Lemma 103 Let (X, p) be a partial metric space and $T : X \rightarrow X$ be a given mapping. Suppose that T is continuous at x_0 . Then, for all sequence $\{x_n\} \subseteq X$, if $\{x_n\}$ converges to x_0 in (X, p) implies $\{Tx_n\}$ converges to Tx_0 in (X, p) .

Definition 3. [9] An element $(x, y) \in X \times X$ is said to be a coupled fixed point of the mapping $T : X \times X \rightarrow X$ if

$$T(x, y) = x \text{ and } T(y, x) = y.$$

Definition 4. [15] An element $(x, y) \in X \times X$ is called a coupled coincidence point of a mapping $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ if

$$T(x, y) = gx \text{ and } T(y, x) = gy.$$

Definition 5. [15] Let X be a non-empty set and $T : X \times X \rightarrow X$ and $g : X \rightarrow X$. We say T and g are commutative if for all $x, y \in X$,

$$g(T(x, y)) = T(gx, gy).$$

H. Aydi [7] obtained the following.

Theorem 1. Let (X, p) be a complete partial metric space. Suppose that the mapping $T : X \times X \rightarrow X$ satisfies the following contractive condition for all $x, y, u, v \in X$

$$p(T(x, y), T(u, v)) \leq kp(x, u) + lp(y, v), \quad (2)$$

where k and l are nonnegative constants with $k + l < 1$. Then, T has a unique coupled fixed point.

The main purpose of this article is to present a generalization of Theorem 1.

2 Existence and uniqueness of coupled coincidence points

In this section, we will prove the existence and uniqueness of the coupled coincidence point. Our first main result is the following:

Theorem 2. Let (X, p) be a complete partial metric space. Assume there exist $a_1, a_2, a_3 \geq 0$ with $2a_1 + 3a_2 + 3a_3 < 2$ and also suppose $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ are such that

$$\begin{aligned} & p(T(x, y), T(u, v)) \\ & \leq a_1 \frac{p(gx, gu) + p(gy, gv)}{2} \\ & + a_2 \frac{p(gx, T(x, y)) + p(gu, T(u, v)) + p(gy, gv)}{2} \\ & + a_3 \frac{p(gx, T(u, v)) + p(gu, T(x, y)) + p(gy, gv)}{2}, \end{aligned} \quad (3)$$

for all $x, y, u, v \in X$. Also Suppose $T(X \times X) \subseteq g(X)$, g is continuous and commutes with T . Then there exist $x, y \in X$ such that

$$gx = T(x, y) \text{ and } gy = T(y, x),$$

that is, T and g have a unique coupled coincidence point.

Proof. Let x_0, y_0 be two arbitrary elements in X . Since $T(X \times X) \subseteq g(X)$, we can choose $x_0, y_0 \in X$ such that $gx_1 = T(x_0, y_0)$ and $gy_1 = T(y_0, x_0)$. Again from $T(X \times X) \subseteq g(X)$ we can choose $x_1, y_1 \in X$ such that $gx_2 = T(x_1, y_1)$ and $gy_2 = T(y_1, x_1)$. Continuing this process, we can construct two sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$gx_{n+1} = T(x_n, y_n) \text{ and } gy_{n+1} = T(y_n, x_n) \text{ for all } n \geq 0 \quad (4)$$

Now, let $a = \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2}$ and $\lambda = \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3}$. Then, by (3), we have

$$\begin{aligned} & p(gx_1, gx_2) = p(T(x_0, y_0), T(x_1, y_1)) \\ & \leq a_1 \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} \\ & + a_2 \frac{p(gx_0, T(x_0, y_0)) + p(gx_1, T(x_1, y_1)) + p(gy_0, gy_1)}{2} \\ & + a_3 \frac{p(gx_0, T(x_1, y_1)) + p(gx_1, T(x_0, y_0)) + p(gy_0, gy_1)}{2} \\ & = a_1 \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} \\ & + a_2 \frac{p(gx_0, gx_1) + p(gx_1, gx_2) + p(gy_0, gy_1)}{2} \\ & + a_3 \frac{p(gx_0, gx_2) + p(gx_1, gx_1) + p(gy_0, gy_1)}{2} \\ & \leq a_1 \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} \\ & + a_2 \frac{p(gx_0, gx_1) + p(gx_1, gx_2) + p(gy_0, gy_1)}{2} \\ & + a_3 \frac{p(gx_0, gx_1) + p(gx_1, gx_2) + p(gy_0, gy_1)}{2}. \end{aligned}$$

Thus, we obtain

$$\begin{aligned} p(gx_1, gx_2) & \leq \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3} \cdot \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} \\ & = \lambda a. \end{aligned}$$

Also, one can get

$$\begin{aligned}
 p(gy_1, gy_2) &= p(T(y_0, x_0), T(y_1, x_1)) \\
 &\leq a_1 \frac{p(gy_0, gy_1) + p(gx_0, gx_1)}{2} \\
 &\quad + a_2 \frac{p(gy_0, T(y_0, x_0)) + p(gy_1, T(y_1, x_1)) + p(gx_0, gx_1)}{2} \\
 &\quad + a_3 \frac{p(gy_0, T(y_1, x_1)) + p(gy_1, T(y_0, x_0)) + p(gx_0, gx_1)}{2} \\
 &= a_1 \frac{p(gy_0, gy_1) + p(gx_0, gx_1)}{2} \\
 &\quad + a_2 \frac{p(gy_0, gy_1) + p(gy_1, gy_2) + p(gx_0, gx_1)}{2} \\
 &\quad + a_3 \frac{p(gy_0, gy_2) + p(gy_1, gy_1) + p(gx_0, gx_1)}{2} \\
 &\leq a_1 \frac{p(gy_0, gy_1) + p(gx_0, gx_1)}{2} \\
 &\quad + a_2 \frac{p(gy_0, gy_1) + p(gy_1, gy_2) + p(gx_0, gx_1)}{2} \\
 &\quad + a_3 \frac{p(gy_0, gy_1) + p(gy_1, gy_2) + p(gx_0, gx_1)}{2}.
 \end{aligned}$$

Thus, we obtain

$$\begin{aligned}
 p(gy_1, gy_2) &\leq \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3} \cdot \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} = \lambda a.
 \end{aligned}$$

Similar to the above proof, one can show that

$$\begin{aligned}
 p(gx_n, gx_{n+1}) &\leq \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3} \cdot \frac{p(gx_{n-1}, gx_n) + p(gy_{n-1}, gy_n)}{2} \\
 &= \lambda \frac{p(gx_{n-1}, gx_n) + p(gy_{n-1}, gy_n)}{2} \\
 &\leq \lambda^2 \frac{p(gx_{n-2}, gx_{n-1}) + p(gy_{n-2}, gy_{n-1})}{2} \\
 &\vdots \\
 &\leq \lambda^n \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} \\
 &= \lambda^n a,
 \end{aligned}$$

and

$$\begin{aligned}
 p(gy_n, gy_{n+1}) &\leq \frac{2(a_1 + a_2 + a_3)}{2 - a_2 - a_3} \cdot \frac{p(gx_{n-1}, gx_n) + p(gy_{n-1}, gy_n)}{2} \\
 &= \lambda \frac{p(gx_{n-1}, gx_n) + p(gy_{n-1}, gy_n)}{2} \\
 &\leq \lambda^2 \frac{p(gx_{n-2}, gx_{n-1}) + p(gy_{n-2}, gy_{n-1})}{2} \\
 &\vdots \\
 &\leq \lambda^n \frac{p(gx_0, gx_1) + p(gy_0, gy_1)}{2} \\
 &= \lambda^n a.
 \end{aligned}$$

If $p(gx_0, gx_1) + p(gy_0, gy_1) = 0$, then from remark 1, we get $gx_0 = gx_1 = T(gx_0, gy_0)$ and $gy_0 = gy_1 = T(gy_0, gx_0)$, meaning that (x_0, y_0) is a coupled coincidence point of T and g . Now, let $p(gx_0, gx_1) + p(gy_0, gy_1) > 0$. For each $m \geq n$ we have in view of the condition (p_4)

$$\begin{aligned}
 p(gx_m, gx_n) &\leq p(gx_m, gx_{m-1}) + p(gx_{m-1}, gx_{m-2}) - p(gx_{m-1}, gx_{m-1}) \\
 &\quad + p(gx_{m-2}, gx_{m-3}) + p(gx_{m-3}, gx_{m-4}) - p(gx_{m-3}, gx_{m-3}) \\
 &\quad + \dots + p(gx_{n+2}, gx_{n+1}) + p(gx_{n+1}, gx_n) - p(gx_{n+1}, gx_{n+1}) \\
 &\leq p(gx_m, gx_{m-1}) + p(gx_{m-1}, gx_{m-2}) + \dots + p(gx_{n+1}, gx_n) \\
 &\leq (\lambda^{m-1} + \lambda^{m-2} + \dots + \lambda^n)a \\
 &\leq \frac{\lambda^n}{1 - \lambda} a.
 \end{aligned}$$

Similarly, we have

$$\begin{aligned}
 p(gy_m, gy_n) &\leq (\lambda^{m-1} + \lambda^{m-2} + \dots + \lambda^n)a \\
 &\leq \frac{\lambda^n}{1 - \lambda} a.
 \end{aligned}$$

Then

$$\lim_{n,m \rightarrow \infty} p(gx_m, gx_n) = 0 \text{ and } \lim_{n,m \rightarrow \infty} p(gy_m, gy_n) = 0. \quad (5)$$

By (1), we have $p^s(x, y) \leq 2p(x, y)$, so for any $m \geq n$

$$\begin{aligned}
 p^s(gx_m, gx_n) &\leq 2p(gx_m, gx_n) \leq 2 \frac{\lambda^n}{1 - \lambda} a, \\
 p^s(gy_m, gy_n) &\leq 2p(gy_m, gy_n) \leq 2 \frac{\lambda^n}{1 - \lambda} a.
 \end{aligned}$$

So,

$$\lim_{n,m \rightarrow \infty} p^s(gx_m, gx_n) = 0 \text{ and } \lim_{n,m \rightarrow \infty} p^s(gy_m, gy_n) = 0. \quad (6)$$

Then $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequences in (X, p^s) . Since the partial metric space (X, p) is complete hence thanks to Lemma 101, the metric (X, p^s) is complete, so there exist $x, y \in X$ such that

$$\lim_{n \rightarrow \infty} p^s(gx_n, x) = 0 \text{ and } \lim_{n \rightarrow \infty} p^s(gy_n, y) = 0. \quad (7)$$

On the other hand, we have

$$p^s(gx_n, x) = 2p(gx_n, x) - p(gx_n, gx_n) - p(x, x).$$

Letting $n \rightarrow \infty$ in the above equation, we get

$$\lim_{n \rightarrow \infty} p(gx_n, x) = \frac{1}{2} p(x, x). \quad (8)$$

On the other hand, we have $p(x, x) \leq p(gx_n, x)$ for all $n \in N$.

On letting $n \rightarrow \infty$. We get that

$$p(x, x) \leq \lim_{n \rightarrow \infty} p(gx_n, x). \quad (9)$$

Using (8) and (9), we get that

$$p(x, x) = \lim_{n \rightarrow \infty} p(gx_n, x) = 0.$$

Similarly, one can show that

$$p(y, y) = \lim_{n \rightarrow \infty} p(gy_n, y) = 0.$$

Thus, we have

$$p(x, x) = \lim_{n \rightarrow \infty} p(gx_n, x) = 0$$

and

$$p(y, y) = \lim_{n \rightarrow \infty} p(gy_n, y) = 0.$$

From (10) and continuity of g ,

$$p(gx, gx) = \lim_{n \rightarrow \infty} p(ggx_n, gx) = 0$$

and

$$p(gy, gy) = \lim_{n \rightarrow \infty} p(ggy_n, gy) = 0.$$

From (4) and commutativity of T and g ,

$$ggx_{n+1} = g(T(x_n, y_n)) = T(gx_n, gy_n)$$

and

$$ggy_{n+1} = g(T(y_n, x_n)) = T(gy_n, gx_n).$$

We now show that $gx = T(x, y)$ and $gy = T(y, x)$.

$$\begin{aligned} & p(gx, T(x, y)) \\ & \leq p(gx, g(gx_{n+1})) + p(g(gx_{n+1}), T(x, y)) \\ & \quad - p(g(gx_{n+1}), g(gx_{n+1})) \\ & \leq p(gx, g(gx_{n+1})) + p(g(T(x_n, y_n)), T(x, y)) \\ & \leq p(gx, g(gx_{n+1})) + p(T(gx_n, gy_n), T(x, y)) \\ & \leq p(gx, g(gx_{n+1})) + a_1 \frac{p(gx, ggx_n) + p(gy, ggy_n)}{2} \\ & \quad + a_2 \frac{p(gx, T(x, y)) + p(ggx_n, T(gx_n, gy_n)) + p(gy, ggy_n)}{2} \\ & \quad + a_3 \frac{p(gx, T(gx_n, gy_n)) + p(ggx_n, T(x, y)) + p(gy, ggy_n)}{2} \\ & \leq p(gx, g(gx_{n+1})) + a_1 \frac{p(gx, ggx_n) + p(gy, ggy_n)}{2} \\ & \quad + a_2 \frac{p(gx, T(x, y)) + p(ggx_n, T(gx_n, gy_n)) + p(gy, ggy_n)}{2} \\ & \quad + a_3 \left[\frac{p(gx, T(gx_n, gy_n)) + p(ggx_n, gx)}{2} \right. \\ & \quad \left. + \frac{p(gx, T(x, y)) + p(gy, ggy_n)}{2} \right]. \end{aligned}$$

Taking the limit as $n \rightarrow \infty$ in above inequality, (11) and (12) we get

$$p(gx, T(x, y)) \leq \frac{a_2 + a_3}{2} p(gx, T(x, y)) < p(gx, T(x, y)),$$

which is a contradiction. Thus, we have $p(gx, T(x, y)) = 0$, which implies that $gx = T(x, y)$. Similarly one can show that $gy = T(y, x)$. Thus we proved that T and g have a coupled coincidence point.

Suppose that (x, y) and (z, t) are coupled coincidence points of T and g , that is

$$gx = T(x, y), \quad gy = T(y, x), \quad gz = T(z, t) \text{ and } gt = T(t, z).$$

We are going to show that $gx = gz$ and $gy = gt$. From condition (3) we have

$$\begin{aligned} p(gx, gz) &= p(T(x, y), T(z, t)) \\ &\leq a_1 \frac{p(gx, gz) + p(gy, gt)}{2} \\ &\quad + a_2 \frac{p(gx, T(x, y)) + p(gz, T(z, t)) + p(gy, gt)}{2} \\ &\quad + a_3 \frac{p(gx, T(z, t)) + p(gz, T(x, y)) + p(gy, gt)}{2} \\ &= a_1 \frac{p(gx, gz) + p(gy, gt)}{2} \\ &\quad + a_2 \frac{p(gx, gx) + p(gz, gz) + p(gy, gt)}{2} \\ &\quad + a_3 \frac{p(gx, gz) + p(gz, gx) + p(gy, gt)}{2} \\ &= \left(\frac{a_1}{2} + a_3 \right) p(gx, gz) + \left(\frac{a_1}{2} + \frac{a_2}{2} + \frac{a_3}{2} \right) p(gy, gt) \\ &\quad + \frac{a_2}{2} (p(gx, gx) + p(gz, gz)) \\ &\leq \left(\frac{a_1}{2} + a_3 \right) p(gx, gz) + \left(\frac{a_1}{2} + \frac{a_2}{2} + \frac{a_3}{2} \right) p(gy, gt) \\ &\quad + \frac{a_2}{2} [p(gx, gz) + p(gz, gx)] \\ &= \left(\frac{a_1}{2} + a_2 + a_3 \right) p(gx, gz) + \left(\frac{a_1}{2} + \frac{a_2}{2} + \frac{a_3}{2} \right) p(gy, gt). \end{aligned}$$

Similarly

$$\begin{aligned} p(gy, gt) &\leq \left(\frac{a_1}{2} + a_2 + a_3 \right) p(gy, gt) \\ &\quad + \left(\frac{a_1}{2} + \frac{a_2}{2} + \frac{a_3}{2} \right) p(gx, gz). \end{aligned}$$

Then above inequality and the property (p_2) , we have

$$\begin{aligned} p(gx, gz) + p(gy, gt) &\leq \left(a_1 + \frac{3a_2}{2} + \frac{3a_3}{2} \right) [p(gx, gz) + p(gy, gt)] \\ &< p(gx, gz) + p(gy, gt), \end{aligned}$$

which is a contradiction. Thus $p(gx, gz) + p(gy, gt) = 0$. It implies that $p(gx, gz) = 0$ and $p(gy, gt) = 0$.

An immediate consequence of Theorem 1 are the following results.

Corollary 201 Let (X, p) be a complete partial metric space. Assume there exist $0 \leq k < 1$ and $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ are such that

$$p(T(x, y), T(u, v)) \leq \frac{k}{2} [p(gx, gu) + p(gy, gv)], \quad (13)$$

for all $x, y, u, v \in X$. Also Suppose $T(X \times X) \subseteq g(X)$, g is continuous and commutes with T . Then there exist $x, y \in X$ such that

$$gx = T(x, y) \text{ and } gy = T(y, x),$$

that is, T and g have a unique coupled coincidence point.

Proof. If T and g satisfies (13), then T and g satisfies (3) with $a_1 = k$ and $a_2 = a_3 = 0$.

Then, the result follows from Theorem 1.

Corollary 202 Let (X, p) be a complete partial metric space. Assume there exist $a_1, a_2, a_3 \geq 0$ with $2a_1 + 3a_2 + 3a_3 < 2$ and also suppose that $T : X \times X \rightarrow X$ is such that

$$\begin{aligned}
 & p(T(x,y), T(u,v)) \\
 & \leq a_1 \frac{p(x,u) + p(y,v)}{2} \\
 & + a_2 \frac{p(x, T(x,y)) + p(u, T(u,v)) + p(y,v)}{2} \\
 & + a_3 \frac{p(x, T(u,v)) + p(u, T(x,y)) + p(y,v)}{2}, \tag{14}
 \end{aligned}$$

for all $x, y, u, v \in X$. Then there exist $x, y \in X$ such that

$$x = T(x,y) \text{ and } y = T(y,x),$$

that is, T have a unique coupled fixed point.

Proof. Putting $g = I$ (I the identity mapping) in Theorem 1, we obtain corollary 202.

Corollary 203 Let (X, p) be a complete partial metric space. Assume there exist $0 \leq k < 1$ and $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ are such that

$$p(T(x,y), T(u,v)) \leq \frac{k}{2} [p(x,u) + p(y,v)], \tag{15}$$

for all $x, y, u, v \in X$. Then T has a unique coupled fixed point.

Corollary 204 Let (X, p) be a complete partial metric space. Assume there exist $0 \leq k < 1$ and also suppose $T : X \times X \rightarrow X$ and $g : X \rightarrow X$ are such that

$$\begin{aligned}
 & p(T(x,y), T(u,v)) \\
 & \leq \frac{k}{2} [p(gx, T(u,v)) + p(gu, T(x,y)) + p(gy, gv)], \tag{16}
 \end{aligned}$$

for all $x, y, u, v \in X$. Also Suppose $T(X \times X) \subseteq g(X)$, g is continuous and commutes with T . Then there exist $x, y \in X$ such that

$$gx = T(x,y) \text{ and } gy = T(y,x),$$

that is, T and g have a unique coupled coincidence point.

Example 3. Let $X = [0, 1]$ endowed with the usual partial metric p defined by $p(x,y) = \max\{x,y\}$. Since

$$\begin{aligned}
 p^s(x,y) &= 2p(x,y) - p(x,x) - p(y,y) \\
 &= \max\{x,y\} - x - y \\
 &= |x - y|,
 \end{aligned}$$

is Euclidean metric, then (X, p^s) is complete. So it is clear that (X, p) is a complete partial metric space. Define $T :$

$X \times X \rightarrow X$ as $T(x,y) = \frac{x+y}{16}$ for all $x, y \in X$ and $g : X \rightarrow X$ be defined by $gx = \frac{1}{2}x$. We show that condition (3) is satisfied.

If $x, y \in X$, then we have

$$\begin{aligned}
 p(T(x,y), T(u,v)) &= \max\left\{\frac{x+y}{16}, \frac{u+v}{16}\right\} \\
 &\leq \frac{1}{16} [\max\{x,u\} + \max\{y,v\}] \\
 &\leq \frac{1}{4} \times \frac{\max\{gx, gu\} + \max\{gy, gv\}}{2} \\
 &\leq a_1 \frac{p(gx, gu) + p(gy, gv)}{2} \\
 &\leq a_1 \frac{p(gx, gu) + p(gy, gv)}{2} \\
 &+ a_2 \frac{p(gx, T(x,y)) + p(gu, T(u,v)) + p(gy, gv)}{2} \\
 &+ a_3 \frac{p(gx, T(u,v)) + p(gu, T(x,y)) + p(gy, gv)}{2}.
 \end{aligned}$$

Thus all the conditions of theorem 1 are satisfied. Moreover, $(0,0)$ is the unique coupled coincidence point of T and g .

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